

Topography and roughness

The surface structure and its roughness are decisive for many applications. Thus a quick and accurate measurement of these properties is essential.

In artificial joint replacements for example, the roughness of articulating surfaces strongly influences the wear which is generated in these devices. In the case of dental and orthopaedic implants, the material and its surface structure particularly determine bone on-growth and therefore its fixation to bone. At the RMS Foundation, we use a modern, optical 3D-measuring device to measure the surface structure and roughness on many kinds of samples. The S neox from Sensofar allows measurements in different modes: interferometry (both phase shift and white light interferometry), confo-

cal microscopy and focus variation. If the lateral resolution of optical systems is not sufficient, then the topography can be assessed by scanning electron microscopy (SEM): Pictures of a surface are acquired at two different tilting angles and thus the topography can be determined semi-quantitatively. Herewith lateral resolutions down to few nanometres can be achieved.

Besides the surface roughness parameters, the more common profile roughness values can be determined by extracting and evaluating multiple profiles from the measured topographies. Several single topographies are usually stitched together to obtain a larger topography, based on which the roughness values can be determined according to ISO standard 21920-3. This can be performed for highly polished surfaces as well as for rough samples.

The S neox is used for various projects, both for testing and research. For example, an artificial ceramic-on-polymer joint was investigated, which was heavily damaged *in vivo* by 3rd-body wear caused by metallic particles, which entered into the articulation. The surfaces were documented using white light interferometry. It was shown that the softer polymer part was heavily scratched (Figure 1) while there was material transferred onto the ceramic part (Figure 2). This material caused a higher roughness which in turn led to more abrasion of the polymer part.

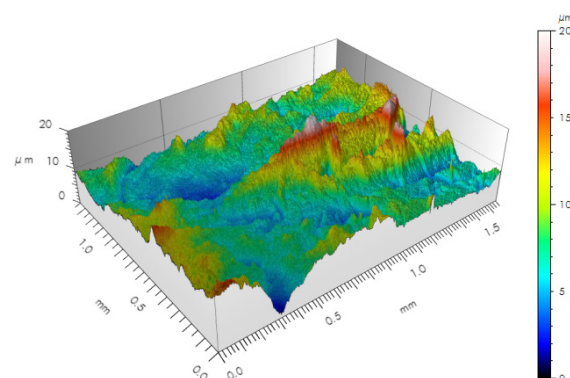


Figure 1: Topography of a scratched (3rd-body wear) polymer implant after explantation

cal microscopy and focus variation. With interferometry – combined with a piezo drive and an active vibration control – depth-resolutions in the sub-nanometre range are possible. Rough samples can be investigated using confocal microscopy and the contour of a sample can quickly be assessed with focus variation. Very large samples can be analysed too, thanks to a

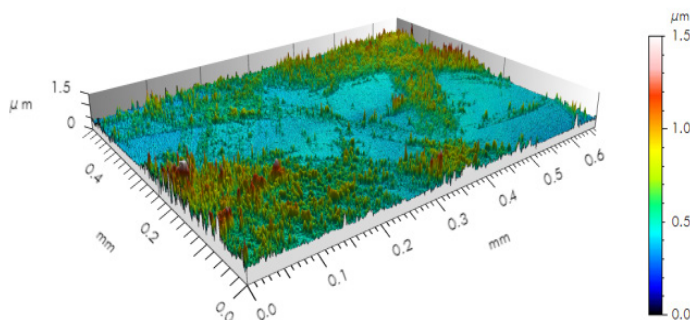


Figure 2: Topography of a ceramic implant: explant with metal transfer

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Optical roughness measurement

Device

S neox from Sensofar (Spain)

Measuring modes

- Interferometry (Phase shift and white light interferometry)
- Confocal microscopy
- Focus variation



Resolution

vertical 0.1 nm with phase shift interferometry
lateral 0.2 µm (100X objective)

Sample requirements

Solid samples
Dimension < 60 x 60 x 60 cm
Weight < 10 kg
Reflectivity 0.05 % to 100 %
Height difference < 40 mm
Lateral movement < 114 x 75 mm

Normative references

Profiles: ISO 21920-1, -2 & -3
Areas: ISO 25178-1, -2 & -3

Feel free to contact us regarding your specific requirements. We are happy to answer your questions. Contact for topography and roughness:

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More information as well as our service catalogue can be found on our website.

The RMS Foundation has been certified according to ISO 9001 and is an ISO/IEC 17025 accredited laboratory type C.

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